Validation Report

Wisconsin, SPS-1 Task Order 20, CLIN 2 November 27 to 28, 2007

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1 Executive Summary

A visit was made to the Wisconsin 0100 on November 27 to 28, 2007 for the purposes of conducting a validation of the WIM system located on SR 29 at approximately 1.25 miles east of Hilltop Road. The SPS-1 is located in the righthand, westbound lane of a fourlane divided facility. The posted speed limit at this location is 65 mph. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This site was a relocation of an existing site located approximately 175 feet downstream from the present site. At the old site, all four lanes are instrumented with bending plate technology. The leading WIM sensor in the LTPP lane at the old site has been removed and the excavation has been filled with asphalt. At this new site, the LTPP lane is the only lane that was instrumented. This is the first validation visit to this location. The site was installed on June 19 and 20, 2007 by International Road Dynamics Inc.

This site meets all LTPP precision requirements except speed. This is not considered sufficient to disqualify the site as having research quality data. The classification algorithm is not currently providing research quality classification information.

The site is instrumented with bending plate and iSINC electronics. It is installed in portland cement concrete. This WIM location also serves to provide traffic data for the SPS-2 site, which is located immediately upstream of the SPS-1 site.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 77,530 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 68,170 lbs., the "partial" truck.

The validation speeds ranged from 53 to 65 miles per hour. The pavement temperatures ranged from 12 to 30 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was not achieved.

Table 1-1 Post-Validation results – 550100 – 28-Nov-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-2.0 \pm 7.5\%$	Pass
Tandem axles	±15 percent	$-0.2 \pm 7.7\%$	Pass
GVW	±10 percent	$-0.5 \pm 5.6\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$0.0 \pm 1.2 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.0 \text{ ft}$	Pass

Prepared: djw Checked: bko

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area. No profile data is provided from which WIMIndex values can be calculated.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	$\pm 20\%$	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

This site needs five years of data to meet the goal of five years of research quality data.

2 Corrective Actions Recommended

This site requires no corrective actions at this time.

3 Post Calibration Analysis

This final analysis is based on test runs conducted November 28, 2007 during the morning and early afternoon hours at test site 550100 on SR 29. This SPS-1 site is at milepost 189.8 on the westbound, righthand of a four-lane divided facility. No autocalibration was used during test runs. The two trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 77,530 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 68,170 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 53 to 65 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 12 to 30 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

As shown in Table 3-1, the site meets and passed all LTPP performance criteria for research quality data for weight and spacing. It did not meet the requirements for speed, which is not considered sufficient to disqualify the site as having research quality data.

Table 3-1 Post-Validation Results – 550100 – 28-Nov-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-2.0 \pm 7.5\%$	Pass
Tandem axles	±15 percent	$-0.2 \pm 7.7\%$	Pass
GVW	±10 percent	$-0.5 \pm 5.6\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$0.0 \pm 1.2 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.0 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during morning and early afternoon hours under mostly cloudy weather conditions, resulting in a limited range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and two temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired

distribution of speed and temperature combinations was not achieved for this set of validation runs.

The three speed groups were divided as follows: Low speed -53 to 55 mph, Medium speed -56 to 61 mph and High speed -62 + mph. The two temperature groups were created by splitting the runs between those at 12 to 22 degrees Fahrenheit for Low temperature and 23 to 30 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

70 68 66 64 62 Speed (mph) ocomb. 60 58 56 52 50 15 20 30 Temperature (F)

Figure 3-1 Post-Validation Speed-Temperature Distribution – 550100 – 28-Nov-2007

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. From the figure, it can be seen that the equipment slightly underestimates GVW at the lower speeds and measures GVW with reasonable accuracy at the medium and high speeds. Variability is notably greater at the medium speeds when compared with low and high speed variability.

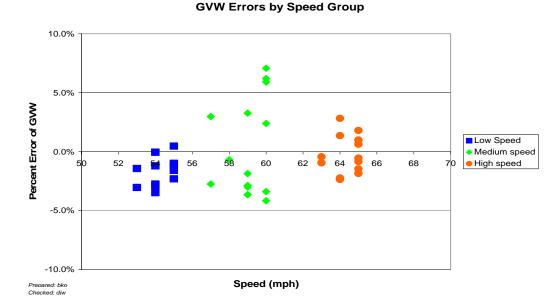


Figure 3-2 Post-validation GVW Percent Error vs. Speed - 550100 - 28-Nov-2007

Figure 3-3 shows the relationship between temperature and GVW percentage error. The graph illustrates that there does not appear to be a relationship between GVW error and pavement temperature.

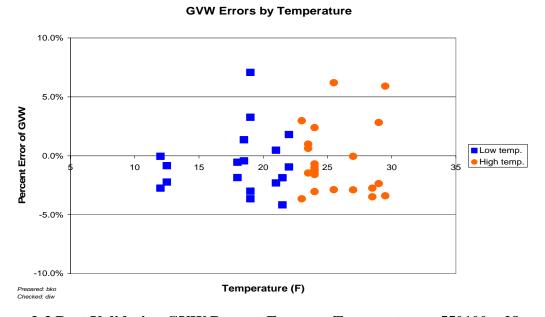


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 550100 – 28-Nov-2007

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the

drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Axle spacing errors appear to be consistent throughout the test truck speed range and are limited to about 0.1 feet. Vehicles speeds appear to have no effect on the error of measured axle spacing.

0.20 0.15 0.00 0.00 0.00 0.00 0.00 0.01 0.00 0.00 0.01 0.00 0

Figure 3-4 Post-Validation Spacing vs. Speed – 550100 – 28-Nov-2007

3.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 12 to 22 degrees Fahrenheit for Low temperature and 23 to 30 degrees Fahrenheit for High temperature.

Table 3-2 Post-Validation Results by Temperature Bin – 550100 – 28-Nov-2007

Element	95% Limit	Low Temperature 12 to 22 °F	High Temperature 23 to 30 °F
Steering axles	<u>+</u> 20 %	-1.7 ± 7.1%	-2.3 ± 8.3%
Tandem axles	<u>+</u> 15 %	$-0.3 \pm 6.8\%$	-0.1 ± 8.6%
GVW	<u>+</u> 10 %	$-0.6 \pm 5.8\%$	$-0.5 \pm 5.9\%$
Speed	<u>+</u> 1 mph	$-0.1 \pm 1.3 \text{ mph}$	$0.0 \pm 1.3 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

Prepared: djw Checked: bko

From Table 3-2, it appears that the mean error for steering axles is greater than the mean error for tandem and GVW weights at all temperatures. The equipment appears to estimate GVW and tandem axle weights with reasonable accuracy. The scatter for all weight errors is greater at the higher temperatures.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph.

The figure illustrates consistent GVW errors for both trucks over the observed temperature range.

GVW Errors vs. Temperature by Truck

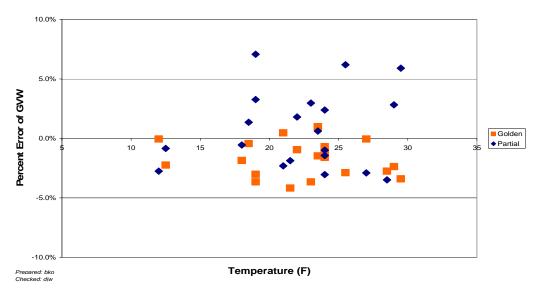


Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 550100 – 28-Nov-2007

Figure 3-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Figure 3-6 shows how the WIM equipment underestimates the steering axle weights at all temperatures. Variability of the error is increasing as the temperature increases. This may be a function of the number of observations rather than an actual temperature effect.

Steering Axle Errors vs. Temperature

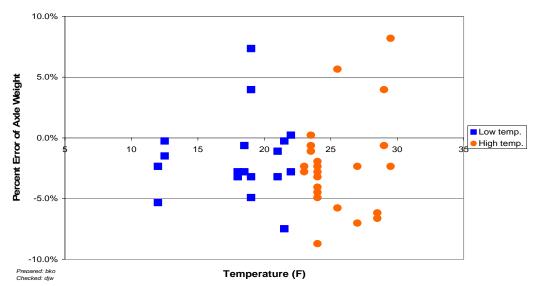


Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group – 550100 – 28-Nov-2007

3.2 Speed-based Analysis

The three speed groups were divided using 53 to 55 mph for Low speed, 56 to 61 mph for Medium speed and 62+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 550100 – 28-Nov-2007

Element	95% Limit	Low Speed 53 to 55 mph	Medium Speed 56 to 61 mph	High Speed 62+ mph
Steering axles	<u>+</u> 20 %	$-3.7 \pm 3.9\%$	-1.5 ± 11.6%	$-0.9 \pm 4.1\%$
Tandem axles	<u>+</u> 15 %	$-1.3 \pm 4.0\%$	$0.7 \pm 11.5\%$	$-0.1 \pm 4.9\%$
GVW	<u>+</u> 10 %	$-1.6 \pm 2.7\%$	$0.1 \pm 8.7\%$	$-0.2 \pm 3.6\%$
Speed	<u>+</u> 1 mph	$-0.2 \pm 1.3 \text{ mph}$	$0.1 \pm 1.3 \text{ mph}$	$0.1 \pm 1.4 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 3-3 it appears that all weights are estimated with reasonable accuracy with the exception of the slight underestimation of weights at the lower speeds. Scatter of the error is much greater at the medium speeds for all weight estimation errors.

Figure 3-7 illustrates the tendency of the WIM equipment to estimate GVW differently for each test truck. For the Golden truck (squares), the equipment estimates GVW with reasonable accuracy at the low and high speeds and underestimates at the medium speeds. For the Partial truck (diamonds), the equipment underestimates GVW at the low speeds, slightly overestimates at the high speeds, and overestimates to a much greater degree at the medium speeds. At the medium speeds, the underestimation of GVW for the Golden

truck when combined with the overestimation of GVW for the Partial truck contributes to a much greater scatter in error for the truck population as a whole at those speeds.

GVW Errors vs. Speed

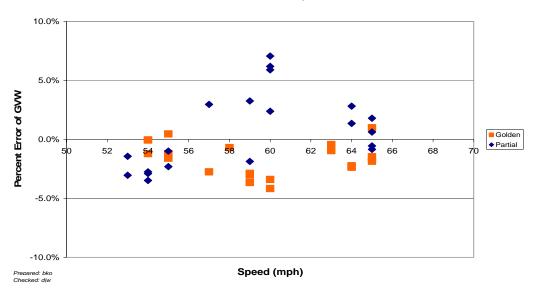


Figure 3-7 Post-Validation GVW Percent Error vs. Speed by Truck-550100-28-Nov-2007

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Figure 3-8 shows how the WIM equipment underestimates steering axle weights at the low and medium speeds and estimates with reasonable accuracy at high speeds. As with GVW, scatter of error is much greater at the medium speeds.

Steering Axle Errors vs. Speed

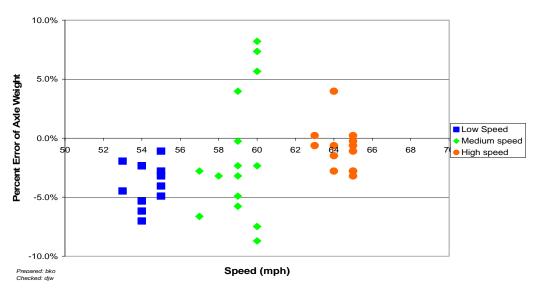


Figure 3-8 Post-Validation Steering Axle Percent Error vs. Speed by Group – 550100 – 28-Nov-2007

Figure 3-9 illustrates the tendency for the equipment to estimate steering axle weights much in the same manner as GVW is estimated. For both trucks, steering axle weights are underestimated at low speeds and estimated with reasonable accuracy at high speeds. At the medium speeds, the opposing estimating tendencies contribute to a much greater scatter in error at those speeds.



Figure 3-9 Post-Validation Steering Axle Errors by Truck and Speed – 550100 - 28-Nov-2007

3.3 Classification Validation

The agency uses the LTPP ETG Mod 3 algorithm to classify vehicles in the FHWA 13-bin classification scheme at this site. Classification 15 has been added to define unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The overall misclassification rate is 11.3 percent. Most of the misclassification errors were related to Class 5 vehicles with short axle spacings. Those vehicles were consistently identified as belonging to Class 4.

Table 3-4 Truck Misclassification Percentages for 550100 – 28-Nov-2007

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	100	5	46	6	13
7	0				
8	0	9	0	10	0
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 Truck Classification Mean Differences for 550100 – 28-Nov-2007

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	UNK	5	- 46	6	- 13
7	0				
8	0	9	0	10	0
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked

Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	$\pm~20\%$	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

4 Pavement Discussion

The pavement smoothness may have contributed to the higher degree of scatter for both GVW and Steering axle error at the medium speeds. In the absence of profile data elimination of smoothness as a possible cause is not possible.

The pavement condition did not appear to influence truck movement across the sensors.

4.1 Profile Analysis

Profile data collected since installation and prior to the site visit do not exist. A site visit to collect profile data has not been scheduled yet. An amended report will be submitted when the data is available.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement, no distresses that would influence truck movement across the WIM scales were noted. The repaired area from the previous bending plate location is beyond the influence area of the sensors.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires of any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes bending plate and iSINC. These sensors are installed in a portland cement concrete pavement.

New WIM sensors, an electronic controller and support components were installed for the LTPP lane at a site approximately 175 feet upstream from the original site since an Assessment was performed on December 14, 2004.

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. All sensors and system components were found to be within operating parameters.

5.2 Calibration Process

Although no calibration iterations were required, one-calibration iteration was performed between the initial 40 runs and the final 40 runs to improve statistics in the medium speed range (56 to 61). This is above the 15th percentile speed.

For this equipment, there are six primary calibration factors. The dynamic compensation factor is increased to account for underestimation of front axle weights at all speeds and is decreased to compensate for overestimation of front axle weights at all speeds.

The five speed point factors are increased or decreased to compensate for underestimation, overestimation or an imbalance in left/right weights at five different speed ranges.

For this site, the starting factors were:

Dynamic Compensation Factor: 103 Speed point factors:

Left	Right
3296	3476
3381	3566
3414	3601
3315	3497
3262	3441
	3296 3381 3414 3315

5.2.1 Calibration Iteration 1

The results of the pre-validation test runs indicated that the equipment was generally underestimating all weights by approximately 5.0% at medium speeds and overestimating weights by 1.0% at the high speeds. For front axle weights, the equipment underestimated by an additional 3.0% at all speeds.

As a result, the primary factors were adjusted to compensate for these errors and the following factors were installed:

Dynamic compensation factor: 106 Speed point factors:

	Left	Right
Speed bin 1:	3296	3476
Speed bin 2:	3381	3566
Speed bin 3:	3571	3767
Speed bin 4:	3278	3459
Speed bin 5:	3262	3441

Speed bin 1, 2 and 5 factors were not adjusted. There was no data to support changes in factors 1 and 5 as those are associated with 50 and 70 mph respectively. The Phase I On-Site Leader made the calculations, determined the new factors and input them into the controller.

The results of the 12 calibration verification runs are shown in Table 5-1. Because of the calibration verification run equipment accuracies, no further calibrations were deemed necessary. A final 28 test runs were conducted to complete the post-validation series of 40 runs.

Table 5-1 Calibration Iteration 1 Results - 550100 - 28-Nov-2007 (08:53 AM)

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-3.9 \pm 5.9\%$	Pass
Tandem axles	±15 percent	$-0.8 \pm 6.9\%$	Pass
GVW	±10 percent	$-1.4 \pm 3.8\%$	Pass
Speed	<u>+</u> 1 mph	$-0.3 \pm 1.4 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft	0.0 ± 0.1 ft	Pass

Prepared: djw Checked: bko

Figure 5-1 illustrates the change in GVW error estimation at medium speed.

GVW Errors by Speed Group

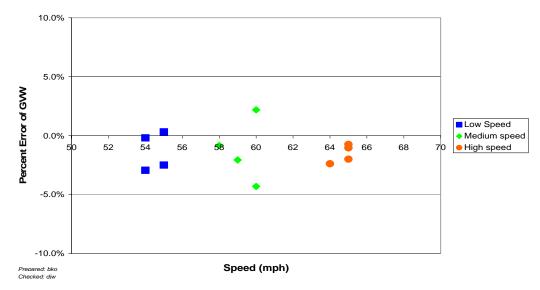


Figure 5-1 Calibration Iteration 1 GVW Percent Error vs. Speed Group – 550100 – 28-Nov-2007 (08:53 AM)

5.3 Summary of Traffic Sheet 16s

This site has validation information only for the current visit in the tables below. Table 5-2 has information for TRF_CALIBRATION_AVC for Sheet 16s for this validation. The data from the Assessment in 2004 is for the previous installation. There no 2004 monitored data available.

Table 5-2 Classification Validation History – 550100 – 28-Nov-2007

Date	Method	Mean Difference				Mean Difference		Percent
Date	Memou	Class 9	Class 8	Other 1	Other 2	Unclassified		
28-Nov-07	Manual	0	0			0		
27-Nov-07	Manual	0	0			0		

Prepared: djw Checked: bko

Table 5-3 has the information for TRF_CALIBRATION_WIM for Sheet 16s submitted for this validation.

Table 5-3 Weight Validation History – 550100 – 28-Nov-2007

Date	Method	Mean Error and (SD)		
Date	Method	GVW	Single Axles	Tandem Axles
28-Nov-07	Test Trucks	-0.5 (2.8)	-2.0 (3.7)	-0.2 (3.9)
27-Nov-07	Test Trucks	-1.8 (3.2)	-5.4 (3.7)	-1.0 (4.1)

Prepared: djw

Checked: bko

5.4 Projected Maintenance/Replacement Requirements

This site is scheduled for semi-annual maintenance under the installation contract. No other maintenance is required at this time.

6 Pre-Validation Analysis

This pre-validation analysis is based on test runs conducted November 27, 2007 during the morning and early afternoon hours at test site 550100 on SR 29. This SPS-1 site is at milepost 189.8 on the westbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 77,870 lbs.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 67,820 lbs., the partial truck.

For the initial validation, each truck made a total of 21 passes over the WIM scale at speeds ranging from approximately 52 to 65 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 10 to 30degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

As shown in Table 6-1, the site meets and passed all LTPP performance criteria for research quality data for weight and spacing. It did not meet the requirements for speed, which is not considered sufficient to disqualify the site as having research quality data.

Table 6-1 Pre-Validation Results – 550100 – 27-Nov-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-5.4 \pm 7.5\%$	Pass
Tandem axles	±15 percent	$-1.0 \pm 8.2\%$	Pass
GVW	±10 percent	$-1.8 \pm 6.4\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$-0.3 \pm 1.7 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.0 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during the morning and early afternoon hours under windy and cloudy weather conditions, resulting in a limited range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and two temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs.

The three speed groups were divided into 52 to 55 mph for Low speed, 56 to 61 mph for Medium speed and 62+ mph for High speed. The two temperature groups were created by splitting the runs between those at 10 to 21 degrees Fahrenheit for Low temperature 22 to 30 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

$Figure\ 6-1\ Pre-Validation\ Speed-Temperature\ Distribution\ -\ 550100\ -\ 27-Nov-2007$

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. From the figure, it can be seen that the equipment underestimates GVW at low and medium speeds. The scatter of the percent error is much greater at the medium speeds.

Prepared: bko Checked: djw

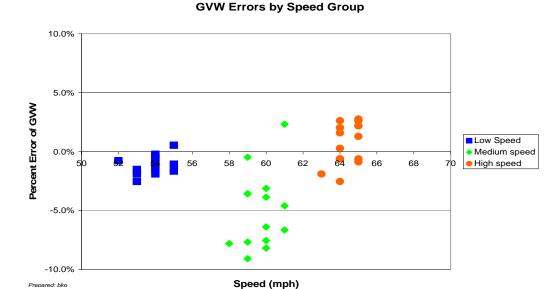


Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 550100 – 27-Nov-2007

Figure 6-3 shows the relationship between temperature and GVW percentage error. The graph illustrates that there does not appear to be a relationship between GVW error and pavement temperature in the observed range.

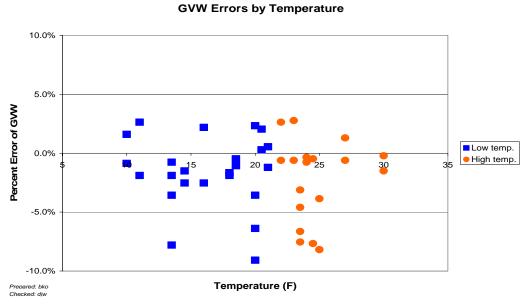


Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 550100 – 27-Nov-2007

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to

correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Axle spacing errors appear to be consistent throughout the test truck speed range and are limited to about 0.1 feet.

Drive Tandem Spacing vs. Radar Speed

Figure 6-4 Pre-Validation Spacing vs. Speed - 550100 - 27-Nov-2007

6.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 10 to 21 degrees Fahrenheit for Low temperature and 22 to 30 degrees Fahrenheit for High temperature.

Table 6-2 Pre-Validation	Results by	Temperature	Bin - 550100 - 27-Nov-	-2007

Element	95% Limit	Low Temperature 10 to 21 °F	High Temperature 22 to 30 °F
Steering axles	<u>+</u> 20 %	$-4.7 \pm 7.4\%$	$-6.2 \pm 8.2\%$
Tandem axles	<u>+</u> 15 %	$-0.8 \pm 7.3\%$	$-1.2 \pm 9.6\%$
GVW	<u>+</u> 10 %	$-1.5 \pm 6.2\%$	-2.2 ± 7.3%
Speed	<u>+</u> 1 mph	$-0.1 \pm 1.9 \text{ mph}$	$-0.5 \pm 1.3 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

Prepared: djw Checked: bko

From Table 6-2 it appears that the equipment underestimates all weights at all temperatures. Scatter in error appears to be slightly greater at the higher temperatures.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. The figure illustrates the tendency of the WIM equipment to report reasonably accurate estimates of GVW weights for the Partial truck (diamonds) while underestimating GVW for the Golden truck (squares) over the entire temperature range. Scatter of error appears

to be greater for the Golden truck when compared with the scatter of error for the Partial truck.

GVW Errors vs. Temperature by Truck

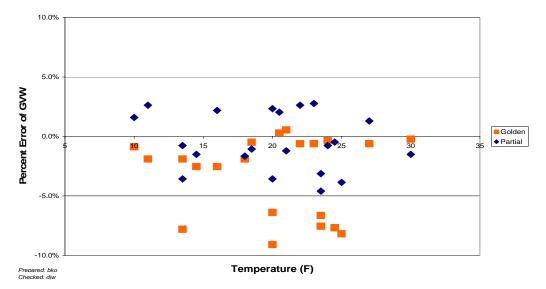


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 550100 – 27-Nov-2007

Figure 6-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure shows how the WIM equipment underestimates the steering axle weights. Variability of the error appears to be consistent, given fewer samples at the upper and lower ends of the temperature range.

Steering Axle Errors vs. Temperature

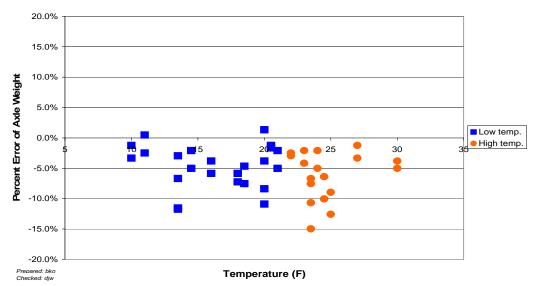


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 550100 – 27-Nov-2007

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -52 to 55 mph, Medium speed -56 to 61 mph and High speed -62+ mph.

Table 6-3 Pre-Validation Results by Speed Bin – 550100 – 27-Nov-2007

Element	95% Limit	Low Speed 52 to 55 mph	Medium Speed 56 to 61 mph	High Speed 62+ mph
Steering axles	<u>+</u> 20 %	$-4.6 \pm 4.0\%$	$-8.8 \pm 8.8\%$	$-2.6 \pm 3.5\%$
Tandem axles	<u>+</u> 15 %	$-0.4 \pm 3.3\%$	-3.9 ± 11.3%	$1.2 \pm 4.8\%$
GVW	<u>+</u> 10 %	$-1.1 \pm 1.8\%$	$-5.0 \pm 7.0\%$	$0.6 \pm 3.9\%$
Speed	<u>+</u> 1 mph	$0.1 \pm 2 \text{ mph}$	$-0.6 \pm 1.6 \text{ mph}$	$-0.3 \pm 1.6 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

Prepared: djw Checked: bko

From Table 6-3, it appears that the mean error and variability in error for all weights is much greater at the medium speeds. Steering axle mean error is greater than GVW and tandem axle error at all speeds.

Figure 6-7 illustrates the tendency of the WIM equipment to estimate GVW differently for each test truck at the medium and high speeds. At the medium speeds, the underestimation of GVW for the Golden truck (squares) is much greater than the underestimation of GVW for the Partial truck (diamonds). At the high speeds, GVW for the Golden truck is estimated with reasonable accuracy while GVW for the Partial truck is overestimated. Scatter for each truck separately is reasonably consistent. The

estimating tendencies of the equipment contribute to a much greater scatter in error for the truck population as a whole at the medium speeds.

GVW Errors vs. Speed

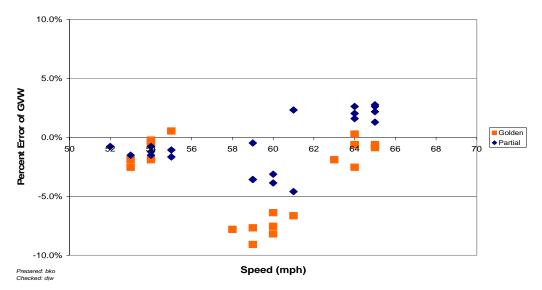


Figure 6-7 Pre-Validation GVW Percent Error vs. Speed Group - 550100 –27-Nov-2007

Figure 6-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure shows how the WIM equipment generally underestimates the steering axle weights and to a greater degree at the medium speeds. Variability of the error appears to be greater at the medium speeds.

Steering Axle Errors vs. Speed

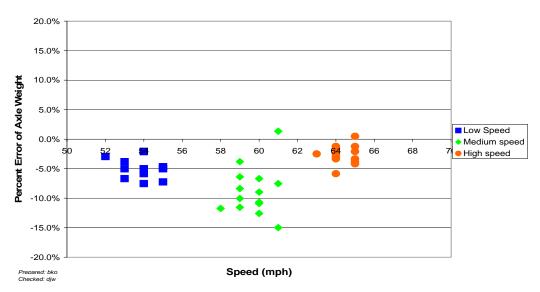


Figure 6-8 Pre-Validation Steering Axle Percent Error vs. Speed Group - 550100 – 27-Nov-2007

Figure 6-9 illustrates the tendency for the equipment to underestimate steering axle weights for both trucks at all speeds. The separation of GVW estimations at the medium speeds shown in Figure 6-7 does not occur with the Steering axle estimations, although the variability in error is still greater at those speeds.

Steering Axle Errors by Truck

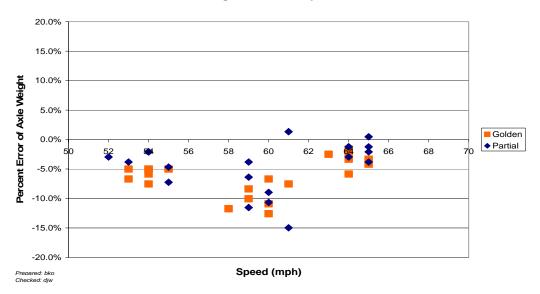


Figure 6-9 Pre-Validation Steering Axle Errors by Truck and Speed $-\,550100-27\text{-Nov-}2007$

6.3 Classification Validation

The agency uses the LTPP ETG Mod 3 algorithm to classify vehicles in the FHWA 13-bin classification scheme at this site. Classification 15 has been added to define unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is 11.3 percent. The errors in classification are associated with short wheelbase Class5s that the equipment bins as Class 4s.

Table 6-4 Truck Misclassification Percentages for 550100 – 27-Nov-2007

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	67	5	33	6	25
7	0				
8	0	9	0	10	0
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them a re matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-5 Truck Classification Mean Differences for 550100 – 27-Nov-2007

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	200	5	- 33	6	- 25
7	0				
8	0	9	0	10	0
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over- or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more

vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	$\pm~20\%$	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

7 Data Availability and Quality

As of November 27, 2007 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site for years prior to installation is not included in this report. There is insufficient data in any year (1998, 1999, 2000 and 2001) to qualify for research quality data. In the absence data from the previous installation, it can be seen that at least five additional years of research quality data are needed to meet the goal of a minimum of 5 years of research weight data.

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 9s and Class 5s constitute more than 10 percent of the truck population. Based on the data collected from the end of the last calibration iteration the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the Regional Support Contractor on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-1 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-1 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.
- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.
- o For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-1 GVW Characteristics of Major sub-groups of Trucks – 550100 – 28-Nov-2007

Characteristic	Class 9	Class 5
Percentage Overweights	1.9%	0.0%
Percentage Underweights	0.2%	2.3%
Unloaded Peak	34,000 lbs	
Loaded Peak	74,000 lbs	
Peak		12,000 lbs

The expected percentage of unclassified vehicles is 0.3%. This is based on the percentage of unclassified vehicles in the post-validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-4. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the post-validation Sheet 16.

Class 9 GVW Distribution

20% 18% 16% 14% Percent per Bin 12% → Class 9 10% 8% 6% 4% 2% 20 ß S Weight in 1000s of pounds Prepared: djw Checked: bko

Figure 7-1 Expected GVW Distribution Class 9 – 550100 – 28-Nov-2007

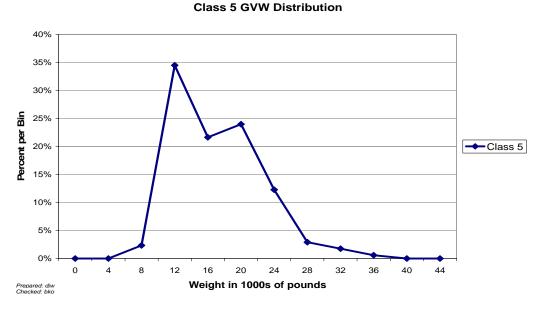


Figure 7-2 Expected GVW Distribution Class 5 – 550100 – 28-Nov-2007

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Vehicle Distribution Trucks (4-15)

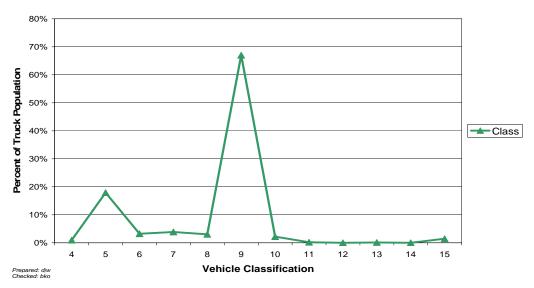


Figure 7-3 Expected Vehicle Distribution – 550100 – 28-Nov-2007

Speed Distribution For Trucks

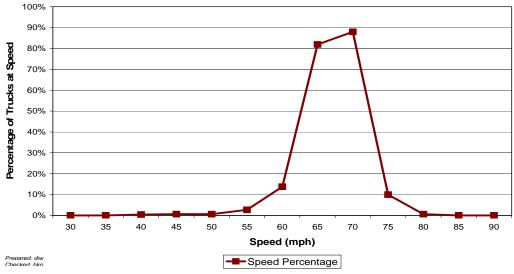


Figure 7-4 Expected Speed Distribution – 550100 – 28-Nov-2007

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

Sheet 19 - Truck 1 - 3S2 loaded air suspension (3 pages)

Sheet 19 – Truck 2 – 3S2 partially loaded air suspension (3 pages)

Sheet 20 – Speed and Classification verification – Pre-Validation (2 pages)

Sheet 20 – Speed and Classification verification – Post-Validation (2 pages)

Sheet 21 – Pre-Validation (3 pages)

Sheet 21 – Calibration Iteration 1 – (1 page)

Sheet 21 – Post-Validation (2 pages)

Calibration Iteration 1 Worksheets – (2 pages)

Test Truck Photographs (6 pages)

LTPP Mod 3 Classification Scheme (1 page)

Final System Parameters (1 page)

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following the next page. It includes a current Sheet 17 with all applicable maps and photographs.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the Pre-Validation and Post-Validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: Wisconsin

SHRP ID: 550100

1.	General Information	1
2.	Contact Information	1
3.	Agenda	1
	Site Location/ Directions	
5.	Truck Route Information	3
	Sheet 17 – Wisconsin (550100)	

Figures

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Figure 6-1 Equipment Layout WI 0100	
Figure 6-2 Site Map of 550100 in Wisconsin	7
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Photo 6-3 Power_Service_Box_55_0100_11_27_07.jpg	
Photo 6-4 Telephone_Box_55_0100_11_27_07.jpg	9
Photo 6-5 Cabinet_Exterior_55_0100_11_27_07.jpg	. 10
Photo 6-6 Cabinet_Interior_Front_55_0100_11_27_07.jpg	. 10
Photo 6-7 Cabinet_Interior_Rear_55_0100_11_27_07.jpg	
Photo 6-8 Leading_WIM_Sensor_55_0100_11_27_07.jpg	
Photo 6-9 Trailing_WIM_Sensor_55_0100_11_27_07.jpg	
Photo 6-10 Leading_Loop_Sensor_55_0100_11_27_07.jpg	
Photo 6-11 Trailing_Loop_Sensor_55_0100_11_27_07.jpg	. 13

Validation – WI 0100 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

1. General Information

SITE ID: 550100

LOCATION: State Highway 29, milepost 189.8.

VISIT DATE: November 27, 2007

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Assessment Team: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: Laura Fenley, 608-246-5455, laura.fenley@dot.state.wi.us

Bill Duckert, 608-246-5440, william.duckert@dot.state.wi.us

Steven Krebs, 608-246-5399, steven.krebs@dot.state.wi.us

John Williamson, 608-267-2939, john.williamson@dot.state.wi.us

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison: Wesley Shemwell, 608-829-7521,

Wesley.shemwell@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: Briefing not requested for this visit

ON SITE PERIOD: Beginning November 27, 2007

TRUCK ROUTE CHECK: Completed by Phase II Contractor at installation

4. Site Location/ Directions

NEAREST AIRPORT: Central Wisconsin Airport, Wausau/Stevens Point, Wisconsin.

DIRECTIONS TO THE SITE: State Highway 29, 1.25miles east of Hilltop Road.

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: US Route 29, milepost 189.8 (Latitude: 44.8508 of and

Longitude: -89.2671⁰)

WIM SITE LOCATION MAP:



Figure 4-1 Site 550100 in Wisconsin

5. Truck Route Information

ROUTE RESTRICTIONS: None.

SCALE LOCATION: Rib Mountain Travel Center (BP station), US 51/SR-29 Exit 188 Wausau, WI; Phone: 715-355-5600, Fax: 715-359-8728, Proprietor: Sharon Klatt;

Latitude: 44.91512, Long: -89.64942; Open 24/7; \$8.50 per weigh.

TRUCK ROUTE:

Eastbound: 1.94 miles to Willow Drive
Westbound: 1.25 miles to Hilltop Road

6. Sheet 17 – Wisconsin (550100)

1.* ROUTE _	<u>US 29</u>	MILEPOST <u>189.</u>	9LTPP D	IRECTION - N S E W
Neares	t SPS section	PTION - Grade <u><1</u> on upstream of the site sor to nearest upstrear	0219	
Distair	ce mom sen	sor to hearest upstrear	ii 3i 3 Section _	1t
3.* LANE CO	NFIGURA	TION		
Lanes	in LTPP di	rection <u>2</u>	Lane width	<u>12</u> ft
Media	<u>3 – </u>	painted physical barrier grass none	Shoulder -	1 – curb and gutter 2 – paved AC 3 – paved PCC 4 – unpaved 5 – none
Should	ler width _	<u>8</u> ft		5 Hone
4.* PAVEME	NT TYPE	portland cement	concrete_	
Date1/27/2 Date F 6. * SENSOR	007 Photo 007 Photo Photo SEQUENC	CE CONDITION – Do 55 0100 Upstream to 55 0100 Downstre	<u>11 27 07.jpg</u> eam 11 27 07.jp g plate – bending	plate loop
REPLAC	EMENT A	ND/OR GRINDING ND/OR GRINDING	/	/
distanc Interse distanc	ction/driver ction/driver ction/driver ce_125' (si	ECTIONS way within 300 m ups way within 300 m downgle house driveway) ely used for turns or pa	vnstream of senso	
9. DRAINAC	GE (Bendin	g plate and load cell s	ystems only)	1 - Open to ground2 - Pipe to culvert3 - None
	-	late <u>6</u> to flush fines from uno		

10. * CABINET LOCATION Same side of road as LTPP lane \underline{Y} / N Median $\underline{Y} / \underline{N}$ Behind barrier $\underline{Y} / \underline{N}$ Distance from edge of traveled lane __30___ ft Distance from system _____ ft TYPE 3M CABINET ACCESS controlled by LTPP / STATE / JOINT? Contact - name and phone number ____John Williamson (608) 267-2939_ Alternate - name and phone number ______ Jane Oldenburg (608) 245-2679_ 11. * POWER Distance to cabinet from drop _____7___ ft Overhead / underground / solar / AC in cabinet? Service provider _____ Phone number _____ 12. * TELEPHONE Distance to cabinet from drop _____7 ___ ftOverhead / underground / cell? Service provider _____ Phone Number _____ 13.* SYSTEM (software & version no.)-Computer connection – RS232 / Parallel port / USB / Other _____ 14. * TEST TRUCK TURNAROUND time ___7__ minutes DISTANCE 6.5 mi 15. PHOTOS **FILENAME** __Power_Service_Box_55_0100_11_27_07.jpg ____ Power source __Telephone_Box_55_0100_11_27_07.jpg _____ Phone source Cabinet exterior __Cabinet_Exterior_55_0100_11_27_07.jpg _____ __Cabinet_Interior_Front_55_0100_11_27_07.jpg _ Cabinet interior __Cabinet_Interior_Back_55_0100_11_27_07.jpg _ __ Leading_WIM_Sensor_55_0100_11_27_07.jpg _ Weight sensors Trailing WIM Sensor 55 0100 11 27 07.jpg Classification sensors ___ __ Leading_Loop_Sensor_55_0100_11_27_07.jpg _ Other sensors Trailing Loop Sensor 55 0100 11 27 07.jpg Description Loop Sensors Downstream direction at sensors on LTPP lane 55 0100 Upstream 11 27 07.jpg Upstream direction at sensors on LTPP lane 55 0100 Downstream 11 27 07.jpg

COMMENTS
GPS Coordinates: Latitude: 44° 51.029' and Longitude: -089 ⁰ 15.997'
Amenities:
Hatley – 3 miles west of site: BP gas, Subway restaurant
<u>Wausau – 20 miles west of site: Various gas stations, hotels,</u>
restaurants, Home Depot
COMPLETED BYDean J. Wolf
PHONE (301) 210-5105 DATE COMPLETED 11 / 27 / 2007

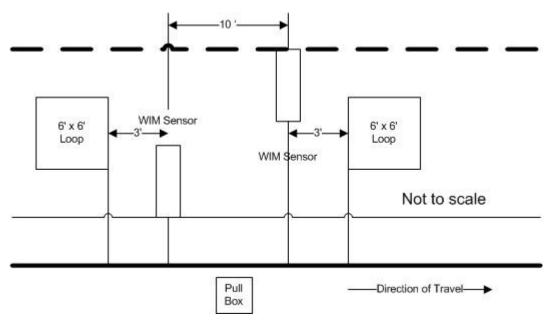


Figure 6-1 Equipment Layout WI 0100

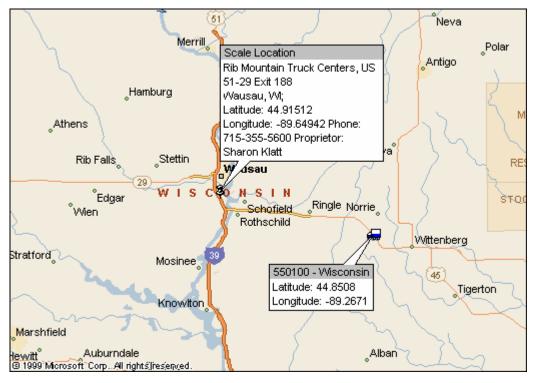


Figure 6-2 Site Map of 550100 in Wisconsin



Photo 6-1 Upstream_55_0100_11_27_07.jpg



Photo 6-2 Downstream_55_0100_11_27_07.jpg



Photo 6-3 Power_Service_Box_55_0100_11_27_07.jpg



Photo 6-4 Telephone_Box_55_0100_11_27_07.jpg



Photo 6-5 Cabinet_Exterior_55_0100_11_27_07.jpg



Photo 6-6 Cabinet_Interior_Front_55_0100_11_27_07.jpg



Photo 6-7 Cabinet_Interior_Rear_55_0100_11_27_07.jpg



Photo 6-8 Leading_WIM_Sensor_55_0100_11_27_07.jpg



Photo 6-9 Trailing_WIM_Sensor_55_0100_11_27_07.jpg



Photo 6-10 Leading_Loop_Sensor_55_0100_11_27_07.jpg



Photo 6-11 Trailing_Loop_Sensor_55_0100_11_27_07.jpg

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>11/27/2007</u>	

1.	DA	ATA PROCESSING –
	a.	Down load – State only LTPP read only LTPP download LTPP download and copy to state
	b.	Data Review – State per LTPP guidelines State – Weekly Twice a Month Monthly Quarterly LTPP
	c.	Data submission – State – Weekly Twice a month Monthly Quarterly LTPP
2.	ΕÇ	QUIPMENT –
	a.	Purchase – State LTPP
	b.	Installation − ☐ Included with purchase ☐ Separate contract by State ☐ State personnel ☐ LTPP contract
	c.	Maintenance – Contract with purchase – Expiration Date _5 years from installation Separate contract LTPP – Expiration Date Separate contract State – Expiration Date State personnel
	d.	Calibration – Vendor State LTPP
	e.	Manuals and software control − ☐ State ☐ LTPP
	f.	Power – i. Type – Overhead Underground Solar ii. Payment – State LTPP N/A

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>11/27/2007</u>	

	g. Communication – i. Type – Landline Cellular Other ii. Payment – State LTPP N/A	
3.	PAVEMENT –	
	 a. Type – Portland Concrete Cement Asphalt Concrete 	
	b. Allowable rehabilitation activities – Always new Replacement as needed Grinding and maintenance as needed Maintenance only No remediation	
	c. Profiling Site Markings – Permanent Temporary	
4.	ON SITE ACTIVITIES –	
	a. WIM Validation Check - advance notice required days week	S
	 b. Notice for straightedge and grinding check	
	ii. Accept grinding – State LTPP	
	c. Authorization to calibrate site – State only LTPP	
	d. Calibration Routine – LTPP – Semi-annually Annually State per LTPP protocol – Semi-annually Annually State other –	

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>11/27/2007</u>	

	e.		Vehicles			
		i.	Trucks – 1st – <u>Air suspension 3S2</u> 2nd – <u>3S2 different weight</u> 3rd – <u>4th – </u>	State ht/suspension State State	□ LTPP □ State □ LTPP □ LTPP	⊠ LTPP
		ii.	Loads –	State		
		iii.	Drivers –	State		
	f.	Contr	ractor(s) with prior successful exp	perience in WIM	I calibration in	state:
		_IRD	_			
	g.	Acces i.	Section State only State only Joint LTPP			
		ii.	Physical Access − ⊠ Key □ Combination			
	h.	State	personnel required on site –	☐Yes ⊠No)	
	i.	Traffi	c Control Required –	☐Yes ⊠No)	
	j.	Enfor	cement Coordination Required –	Yes No)	
5.	SI'a.		ECIFIC CONDITIONS – s and accountability –			
	b.	Repoi	rts –			
	c.	Other	·			
	d.	Speci	al Conditions –			
6.	CC	ONTAC	CTS –			
	a.	Equip	oment (operational status, access,	etc.) –		
			Name: Roy Czinku	Pho	ne: <u>(306) 653-6</u>	6627
			Agency: <u>IRD</u>			

SHEET 18	STATE CODE	[55]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>11/27/2007</u>	

b.	Maintenance (equipment) –	
	Name: Roy Czinku	Phone: (306) 653-6627
	Agency: <u>IRD</u>	
c.	Data Processing and Pre-Visit Data –	
	Name: Roy Czinku	Phone: (306) 653-6627
	Agency: <u>IRD</u>	
d.	Construction schedule and verification –	
	Name:	Phone:
	Agency:	
e.	Test Vehicles (trucks, loads, drivers) –	
	Name: Greg Guite	Phone: 715-849-4000
	Agency: Elite Carriers, LLC	<u>.</u>
f.	Traffic Control –	
	Name:	Phone:
	Agency:	
g.	Enforcement Coordination –	
	Name:	Phone:
	Agency:	
h.	Nearest Static Scale	
	Name: Rib Mountain Travel	Location: <u>US 51/SR 29 (Exit 188)</u>
	<u>Center</u>	
	Phone: 713-359-8728	

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[55]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

1. *	* DATE OF CALIBRATION (MONTH/DAY/YEAR) []	
2. *	* TYPE OF EQUIPMENT CALIBRATED WIM CLASSIFIERX _ BO	ГН
	* REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT RESEARCH EQUIPMENT REPLACEMENT TRAINING DATA TRIGGERED SYSTEM REVISION NEW EQUIPMENT INSTALLATION OTHER (SPECIFY) LTPP Validation	
_ _ _	* SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CHECK ALL THAT APPLY): BARE ROUND PIEZO CERAMIC BARE FLAT PIEZO X BENDING PLATES CHANNELIZED ROUND PIEZO LOAD CELLS QUARTZ PIEZO CHANNELIZED FLAT PIEZO X INDUCTANCE LOOPS CAPACITANCE PAI OTHER (SPECIFY)	DS
5. E	EQUIPMENT MANUFACTURERIRD/ PAT Traffic	
	WIM SYSTEM CALIBRATION SPECIFICS**	
6.**C	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N) _X TEST TRUCKS	
	NUMBER OF TRUCKS COMPARED 2 NUMBER OF TEST TRUCKS USE	D
	TYPE PER FHWA 13 BIN SYSTEM 1 9 1 SUSPENSION: 1 - AIR; 2 - LEAF SPRING 2 9 1 3 - OTHER (DESCRIBE) 3	
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS A PERCENT) MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW	
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATION WAS PERFORMED	
9.	DEFINE THE SPEED RANGES USED (MPH)556065	
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW SPEED)3315 / 3497	
11.**	* IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) N_ IF YES, LIST AND DEFINE AUTO-CALIBRATION VALUE:	
	CLASSIFIER TEST SPECIFICS***	
12.**	** METHOD FOR COLLECTING INDEPENDENT VOLUME MEASUREMENT BY VEHICLE CLASS: VIDEO PARALLEL CLASSIFIERS	
13.	METHOD TO DETERMINE LENGTH OF COUNT TIMEX NUMBER OF TRUC	CKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHICLES CLASSIFICATION: *** FHWA CLASS 9 0.0	
	*** PERCENT "UNCLASSIFIED" VEHICLES: <u>0.0</u>	
	RSON LEADING CALIBRATION EFFORT:Dean J. Wolf, MACTEC	9, 1999
1		

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[55]
*SHRP SECTION ID	[0100]

SITE CALIBRATION INFORMATION

1. *	DATE OF CALIBRATION (MONTH/DAY/YEAR) [11/28/2007]
2. *	TYPE OF EQUIPMENT CALIBRATED WIM CLASSIFIERX BOTH
- -	REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X OTHER (SPECIFY) LTPP Validation RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
- -	SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CHECK ALL THAT APPLY): BARE ROUND PIEZO CERAMIC CHANNELIZED ROUND PIEZO CHANNELIZED FLAT PIEZO X INDUCTANCE LOOPS CAPACITANCE PADS OTHER (SPECIFY)
5. I	EQUIPMENT MANUFACTURER IRD/ PAT Traffic
	WIM SYSTEM CALIBRATION SPECIFICS**
6.**(CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N) _X_ TEST TRUCKS
	NUMBER OF TRUCKS COMPARED 2 NUMBER OF TEST TRUCKS USED
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS A PERCENT) MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW0.5 STANDARD DEVIATION2.8 DYNAMIC AND STATIC SINGLE AXLES2.0 STANDARD DEVIATION3.7 DYNAMIC AND STATIC DOUBLE AXLES0.2 STANDARD DEVIATION3.9
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)556065
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW SPEED)3315 / 3497
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) N IF YES, LIST AND DEFINE AUTO-CALIBRATION VALUE:
	CLASSIFIER TEST SPECIFICS***
12.**	* METHOD FOR COLLECTING INDEPENDENT VOLUME MEASUREMENT BY VEHICLE CLASS: VIDEOX_ MANUAL PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT TIME NUMBER OF TRUCKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHICLES CLASSIFICATION: *** FHWA CLASS 9 0.0
	*** PERCENT "UNCLASSIFIED" VEHICLES: <u>0.0</u>
	SON LEADING CALIBRATION EFFORT: Dean J. Wolf, MACTEC
(0)	NTACT INFORMATION: <u>301-210-5105</u> rev. November 9, 1999



Sheet 19	* STATE_CODE 55
LTPP Traffic Data	* SPS PROJECT ID 0400 0 200
*CALIBRATION TEST TRUCK #_1 Rev. 08/31/01	* DATE 11/2#07
PART I.	Tractor 243 Franter 375
1.* FHWA Class 2.* Number of Axles	Number of weight days 2
AXLES - units lbs 100s lbs / kg	
GEOMETRY	
8 a) * Tractor Cab Style - Cab Over Engine / Conventional	
9. a) * Make: b) * Model:	<u> </u>
10.* Trailer Load Distribution Description:	
11. a) Tractor Tare Weight (units): b). Trailer Tare Weight (units):	
12.* Axle Spacing – units m / feet and inches (feet an	nd tenths
A to B B to C	C to D 32.8
D to E	E to F
Wheelbase (measured A to last)	Computed <u>58,2</u>
13. *Kingpin Offset From Axle B (units) (+ is to t	the rear)
SUSPENSION	
Axle 14. Tire Size 15.* Suspension Description ((leaf, air, no. of leaves, taper or flat leaf, etc.)
18.20 6	
- with the state of the	
· · · · · · · · · · · · · · · · · · ·	
ar proposition of the contract	
F	

		Sheet 19	* ST	ATE_CODE	55		
		PP Traffic Data	····		'S PROJECT ID	0,1 0 0 626	Ó
D 00/21/0		ION TEST TRI	JCK #_1_	* D	ATE 11/	W07	· · ·
Rev. 08/31/0	1						
PART II				Day 1			
	*c) Post Tes	Pre-Test Loa t Loaded Wei ce Post Test -	ght	78050 -77700 -350 347			
Гаble 5. Ra	aw data – Axle	scales – pre-	est				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
l	12020	15430	15430	17590	17590		78060
2	1/930	15440	15440	17590	17590		78090
3	11980	15440	15440	17590	17540		78040
Average	11996	15440	1544,0	17590	17590		78050
	93	31	31				47
Гable 6. Ra	nw data – Axle	scales –					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
	11800	15360	15360	17590	17590		77700
2							
			·		1		

ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11800	15360	15360	17590	17590		77700
2							
3							
Average	1 200	16360	15360	175an	17590		77700

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2					·		
3							
Average							

Measured By	Verified By	W	Weight date	(1	27	0.
			-	-	, ,	

		Sheet 19	* ST	* STATE_CODE 55				
	LT	PP Traffic Data			S PROJECT ID	91 0 0 02	.o2	
		ION TEST TRU	JCK #_ <u>1</u>	* D/	ATE 11.	/28/07		
Rev. 08/31/01								
				Day 2				
7.2	*c) Post Tes	"b) Average Pre-Test Loaded weight			17647 17420 127			
<u> Гаble 5.2. F</u>	<u> Raw data – Ax</u>	le scales – pre	-test					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	
<u> </u>	11760	15340	15340	17660	17600		77640	
2	4740	15360	15360	17590	17590		77640	
3	11740	15360	15360	17600	17600		77660	
Average	11747	1513-393	19353	17597	17597		77647	

Table 6.2. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
, I. 7)	11600	15290	15290	17620	17620		77420
2							
3							
Average	11606	15290	15290	17620	17620		77420

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Measured By	Verified By	Weight date 1124	100/
-------------	-------------	------------------	------

Sheet 19	* STATE_CODE 55
LTPP Traffic Data	* SPS PROJECT ID 0100 0200
*CALIBRATION TEST TRUCK #_2 Rev. 08/31/01	* DATE 11/ / 07
PART I.	mule 498 Pertor
1.* FHWA Class 2.* Number of Axles	Number of weight days 2
AXLES - units - (b) / 100s lbs / kg	
GEOMETRY	
8 a) * Tractor Cab Style - Cab Over Engine Conventional	b) * Sleeper Cab? (Ŋ/N
9. a) * Make: <u> </u>	
10.* Trailer Load Distribution Description:	t.
11. a) Tractor Tare Weight (units):	·
b). Trailer Tare Weight (units):	
12.* Axle Spacing – units m / feet and inches / feet and	tenths
A to B 16.9 B to C 44 4.3 WO C	C to D 32.0
	to F
Wheelbase (measured A to last) Co	omputed <u>57. 3</u>
13. *Kingpin Offset From Axle B (units) (+ is to the	() rear)
SUSPENSION	
··· ·· ·· ·· ·· ·· ·· ·· ·· ·· ·· ·· ··	af, air, no. of leaves, taper or flat leaf, etc.)
A 75225 Zleaf steel	
C 757215 911	
F ²	

		Sheet 19			* STATE_CODE 55				
		PP Traffic Data	ICIZ # 2	,,,	S PROJECT ID	0100 0200			
ev. 08/31/01	·····	TION TEST TRU	UK #_2_		ATE 11/1/07			······································	
ART II									
				Day 1					
	*!-\	Due Treet I ac	مالدان المالدان	6798	^				
		Pre-Test Load t Loaded Weig	_	6766					
		ce Post Test –	-	- 32					
able 5. Ra	w data – Axle	scales – pre-t	est						
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW		
	11700	15710	15710	12450	12450		68020		
	11640	15730	15730	12430	12430		67960		
	11720	15690	15690	12430	12430		67960		
verage	11690	15710	15710	12440	12440		67980		
	81			31	31			1	
abla 6 Pa	w data – Axle	cooles 10 X	Jest						
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW	67	
						AXICF	 	67	
	1/600	15610	15610	12420	12420		67660		
verage	1,600	15610	15610	12420	12420		67660		
			, , , , , , , , , , , , , , , , , , , ,	1 2 1	1 16-1-0		1		
ahle 7 Ray	w data – Axle	ecales nost i	teet						
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW		
	TIMOTE	TAIC D	TAIC	AXICD	AXICL	AXIC	G V W		

				-					

verage									

	Sheet 19	* STATE_CODE 55	٦
	LTPP Traffic Data	* SPS PROJECT ID 0100 0200	
	*CALIBRATION TEST TRUCK #_2_	* DATE 11/2 07	
Rev. 08/31/0	1		
		Day 2	
7.2	*b) Average Pre-Test Loaded weight *c) Post Test Loaded Weight *d) Difference Post Test – Pre-test	68301 68040 261	

Table 5.2. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11880	15810	しうタロロ	12810	1260		68320
2	11940	15770	15770	12418	124/0		68300
3	11886	15810	15810	12400	12400		68300
Average	19900	15791	16197	12407	12407		68307

Table 6.2. Raw data - Axle scales - port feet

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
	11760	15130	15130	12410	12410		68040
2							•
3							
Average	11760	15730	15730	12410	12410		68040

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1		***					
2						199	
3							
Average							

A	-th 4 1 . s	2 .4	1 1 1
Measured By Ver	rified By	Weight date <u> </u>	<u> 2401</u>

Sheet 20	* STATE_CODE	55
LTPP Traffic Data	*SPS PROJECT_ID	0100 0200
Speed and Classification Checks * 1 of* 2	* DATE	11 /27 /2007

S/ = Cing

Rev. 08/31/2001

WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class
4n	9	24199	רט	9	62	9	25292	62	9
59	Ч	24200	Ja 59	5	٣٦	Ч	25312	64	5
63	4	24203	62	4	68	5	25313	69	ς
60	4	24204	60	Ч	70	7	25314	70	"A Long H
65	9	24212	64	9	65	9	25318	67	9
6 5	9	24218	65	٩	41	5	3 5321	39	5
64	٩	24219	64	প	59	9	25324	59	9
6 7	9	24221	67.	٩	57	6	25327	162	6
64	9	24222	64	৭	68	9	25326	3 2	9
4	89	24240	63	9	65	9	25329	60	4
(₈ 3	9	24247	62	9	64	5	25331	6 5	5
59	٩	24250	53	7	50	9	25334	51	9
SY	9	24251	52	٩	67	8	25339	67	8
62	q	25252	62	9	65	9	25342	66	9
Q &	7	25 25 4	\q		<u>(8</u>	5	25343	i 6	5
4 5	g	25 25 5	45	7	64	9	25346	62	9
65]	25256	67	7	৫৩	9	25349	69	9
b 9	9	25262	70	9	64	O _l	25353	65	9
64	9	25263	65	Op	70	5	25354	70	5
(o	3	25274	61	9	68	6	25355	69	6
(₄ (₄	9	25261	66	9	66	9	25357	44	9
65	5	25285	45	5	63	q	25358	Š	9
65	9	25267	\$ 5	q	7.0	જ	75360	· 7.	ő
65	9	25269	65	9	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	9	25365	.10	9
64	9	25290	65	9	70	Ч	25366	69	4
Recorded	1			ection <u>W</u>	<u> </u>		from <u>4220</u>	č.	

9:35

2:36

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Sheet 20	* STATE_CODE	55
LTPP Traffic Data	*SPS PROJECT_ID	201000200
Speed and Classification Checks * 2 of* 2	* DATE	_11 / 27 / _2007

25.7

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	
69	9	25368	66	9	65	Z9	25457	66	- C	
57	9	25381	60	S	60	9	25458	60	9	
(¢5	9	25382	68	9	63	9	25463	45	e s j	
65	9	25385	(4 b)	Q	67	8	25464	67	8	
65	9	25386	65	9	67	S	25465	66	₹\	
66	9	25388	67	9	68	9	25466	69	9	
\begin{align*} 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \	9	25395	61	9	65	9	25472	47	9	
59	5	7.5397	60	5	૯૧	9	25474	69	9	
68	9	25399	68	9	69	9	ZSYTS	68	9	
63	9	25408	64	9	(g (q	9	25476	67	9	
62	્	25416	65	9	67	9	25477	67	9	
(e0	9	25418	(6)	9	64	9	25486	63	9	
70	9	725419	70	9	67	4	25488	<i>ل</i> م	5	21.1
65	9	25421	70	9	Q Q	q	25489	68	٩	
68	4	2542 3	69	6	69	9	25498	(3	9	
65	6	25426	(,5	(,,	67	9	25499	اک	9	
61	9	25427	64	9	69	٩	25502	(,9	9	
61	4	25430	\u \	5	59	চ	25512	57	Š	
64	7	2.5431	(,3	9	(J)	9	25525	67	9.	
45	9	25436	6H	9	49	ij	25527	69	5	04 ZZ 5
63	b १	2544 3	65	15 9	39	5	25532	37	25	76
<u></u>	5	25451	63	5	67	5	72.5541	68	5	
45	9	25452	for high	9	45	9	25543	(3	9	
þ5	9	25453	66	9	43	9	25557	63	9	
√ 1	9	25456	4-7	9	63	10	25558	62	10	

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6420060018_SPSWIM_TO_20_55_2.90_0100_post-Validation_Sheet_20.doc

Sheet 20	* STATE_CODE	55
LTPP Traffic Data	*SPS PROJECT_ID) 0100 ozoo
Speed and Classification Checks * 1 of* 2	* DATE	11 /27 /2007

WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class	
66	9	28531	67	9	66	9	28617	65	9	
60	q	28535	61	9	67	9	28619	65	9	
65	9	28539	65	O _I	63	9	28620	63	લ	
62	q	28543	62	Ŷ	65	6	28621	64	6	
66	9	28548	66	٩	(ગ	9	28627	66	9	
70	9	28557	70	9	64	9	28647	64	9	
68	9	28558	68	9	66	9	28650	66	9	
64	9	28560	(, 3	9	68	9	28653	68	9	
64	9	78864	64	٩	64	9	28654	64	9	
45	(6	28565	45	(0	64	9	28661	62	9	
6 5	9	28566	65	9	64	8	28662	64	8	
65	9	28569	طی	9	67	9	28666	65	9	
68	В	28570	68	S	67	٩	28668	46	9	
66	9	28571	65	9	68	4	28672	69	6	72.9
65	ષ્ઠ	28580	65	8	64	9	28673	64	9	
68	6	28584	68	(4	65	9	28681	47	٩	
67	169	Z8595	68	9	65	9	28685	66	9	
46	9	28598	4	9	66	9	28683	68	9	
GH	S	28599	65	9	69	10	28684	69	10	
65	9	26600	66	9	70	5	28686	٩٧	5	
65	9	28607	64	9	68	E	28688	69	8	
64	ч	Z & 609	i 5	5	62	9	28691	63	9	
70	5	28611	70	5	64	9	28692	63	9	
68	H	28612	69	5	69	9	28696	69	9	
66	9	28616	66	9	60	9	28710	60	9	

21.8

22.8

Recorded by 0.W Direction W Lane 1 Time from 1:10 to 2:15

Sheet 20	* STATE_CODE	55
LTPP Traffic Data	*SPS PROJECT_ID	_01000200
Speed and Classification Checks * of*	* DATE	_11/27/_2007

	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
	60	9	2871)	le l	9	67	6	28768	68	6
3.le	67	4	28713	68	5	70	9	28769	70	9
	65	٩	28716	66	9	70	9	28773	70	9
	65	9	28717	65	٩	67	9	28779	68	9
با.ل	69	4	28718	69	5	65	9	28786	iv	9
	66	٩	28730	67	9	65	9	28787	65	c)
	67	9	Z873 l	67	9	65	9	28788	66	9
	65	6	26732	614	6	63	9	28798	63	4
	70	9	28739	70	Ĵ	67	প	23799	67	9
	68	5	28740	71	5	63	S	28802	64	5
	65	6	28741	64	6	67	٩	28804	66	9
	64	9	28742	63	9	65	9	28809	44	9
	65	9	28744	65	9	٦٦	9	26810	<i>\</i> S	G
Ч	67	リ	28745	67	5	62	5	78811	63	5
	66	9	28749	68	9	66	00	28814	66	8
	68	10	28752	67	\0	64	٩	20017	64	9
	5	0 /	28753	62	10	6 6	9	28819	66	9
	62	9	28754	63	9	G 8	5	26821	L7	5
	64	9	28755	64	9	68	9	28828	60	9
	68	7	28758	69	7	64	9	28 830	66	9
	70	ક	28759	69	8	59	6	26831	59	6
	70	9	26763	711	219	67	9	28833	67	9
	60	9	28764	(e0	9	65	9	28634	4 5	9
	68	9	28766	68	9	65	G	2684)	65	9
	65	9	28767	66	9	61	9	28842	61	9

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				-	space		
	65			D-E	space	٥.٢	
55	0450 0450				space space	71.7 N.0 4.3 32.8 4.0	
	0	7000		B-C		4.3	
		11 / 27 / 2007		A-B	space	٥٠٢١	
ODE	CT ID			GVW		r. F	
* STATE CODE	*SPS PROJECT ID	* DATE		Axle F	weight		
×S.	*SF	*		Axle E	weight.	8.8/9.0	7:
 				Axle D	weight.	4.6/	, , ,
				Axle C	weight.	1.5/1.8	, ,
		æ		AXIBA AXIB AXIBC AXIBD AXIBE AXIBF GVW	weight.	9-1/62	0
		f of 3		Axle A	weight.	5.7/ 1.7/ 1.5/2 8.4/4 8.8/0.0	
21	ic Data	cords		MIM	Speed	1	
Sheet 21	LTPP Traffic Data	Truck Re		Record WIM	o Z	1 8:53 24075 5 H	
	C	tem Test		Time		8:53	
		WIM Sys		Pass		× 4	
		•		Radar Truck			
			Rev. 08/31/2001	Radar	obeed	Sq	_
			Rev. 08	Pvmt	di Hai	30 Sy	

E-F space																
D-E E s	۲.0	ーデ	٩.٠	0	0	 <u>;</u>	0,7	4.0	0, 7	0.7	6.	e. Ť	٥٠٦	۲.0	۲.0	4.0
C-D space	32.8	\$2.0	32.9	32.1	32.6	32.0	 	31.7	\$22.9	32.0	32.6	0.25	32.9	31.9	72.7	3.9
B-C space	4.3	H. 3	Ł.3	4.3	<u>4.3</u>	4.3	ال اع	4.3	4.3	4.3	۲ ۲	4.3	4.3	۲	4.3	2 7
A-B space	٥٠٢١	0.17	1,0	17.0	Ē	16.9	17.0	16.9	17.1	0. L)	0.6	0.٢)	17.0	ję. 9	٥.٢)	16.9
GVW	71.77	66.8	TI.S	65.2	77.2	68.9	76.4	5 E	71.0	F. S9	76.4	69.6	76.4	66.7	70.8	L 5.7
Axle F weight																
Axle E weight.	8.8/	5.4/	8.7/	4.1/ 5.4	2.9/0.6	۴.3/ ۲.4	8.4/	6.3/5.8	3.2/8.3	و: بر و: بر	9-1/8.5	7.0/	8.9/	7.3/5.6	8.4/	ل.ن <i>ا/د</i> ی
Axle D weight.	8.4/ P.9/	ره.نم/ ارف.ن	1.8/	7.1/6.0	8.7/	1.0/	6.3/	1.5/	7,1/8.3	2.1/1.7	6.6/	2.3/1.7	6.8/	1.0/	1.1	1.8/2.7
Axle C weight.	1.5/7.8	8.0/ 7.7	2.7/5.5	8.0/ 7.0	7.7	8.1/28	1'8/ 8'1	8.4/	7.3/	4.9/1.7	7.6/	6.3/ 7.8	7.8/	6.5/	T.4/	7.5/
Axle B weight.	1.7/ 1.6	8.0/2.3	£:L/6:7	ع ^{بر} /چر	P.P/7.9	6.1	5'1/3.1	2.1/5/8	1.7/	5.1/5.1	H.F/	8-3/	7.8/ 7.7	8.2/	F.C/1.1	S.F/2.5
Axle A weight.	5:1/ 6.6	5.2/6.0	15/	2:5/h/s	5.8/	5.5/	5.8/5.7	5.4/	2.3/	2.3/1.5	6.0/ 0.5/	5.7/6.0	h'5/8·5	2.5/2.5	5.3/ h.3	6.3/8.3
Speed	८५	53	59	۵٩	روح	3	74	SH	59	59	カの	63	25	hS	65	528
Record No.	STOWS	24076	24141	24142	24218	2422	05.245	152472	09247	19247	llEhZ	2H313	24332	24333	24357	24358
Time	8:53	8:53	9:08	9036	7235	22:1,	9:30	9:30	9:31	4.37	hth:b	9:14	4:52	9:52	00:01	\$0:01
Pass	-		7	7	n	~	7	て て	N	N	+	د		_	<i>0</i> 0	00
Truck		7		Ц		7		2		7		7		7		7
Radar Speed	Sa	53	0 9	0)	62	بح	3	25	ţ	24	~	(S	5 ₄	55	59	54
Pvmt temp	30	30	25	25	0)	01	13,5	13.5	13.5	13.5	11.0	11.0	18.0	0.81	20.0	20.0

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Sheet 21	* STATE_CODE	55
LTPP Traffic Data *SPe	*SPS PROJECT_ID	070 970

E-F space																
D-E space	4.0	0. J	4.0	ر ا	4.0	٦. ٩	O ÷	۲.0	ч. о	٥٠ ٢	<u>۲.</u> ه	(' ' ' '	Ч.0	4.0	ر -	٩.6
c-D space	37.8	31.9	32.8	31.9	32.1	31.9	32.7	31.9	X.6	51.9	32.7	32.0	32.8	32.0	72.7	32.0
B-C space	4,3	ч. 3	4.3	H.3	ų.3	4.3	H.3	H3	2,	4.3	4.3	£.3	4.3	H.3	4.3	r. 3
A-B space	ت.	16.9	17.0	6.9)	0.77	0.17	0.57	7 to .9	0.17	17.0	0.17	17.0	0.[17.0	0.61	0.11
@VW	78.1	69.2	78.3	0-29	72.1	64.7	4.۲۲	68.7	75.9	66.8	72.0	65.7	77.4	69.6	77.6	67.3
Axle F weight																
Axle E weight.	4.3/	1.1/6.2	8.1/	6.1/	8.3/8.3	7.9/5.6	9.1/8.2	7.1/	5.4/	6.8/ /6.0	8.0/	6.2/6.2	9.8/	الم	1.2/8.5	1.3/ 6.1
Axle D weight.	9.0/	7.0/5.5	62/	6.4/	7.6/	2.2/2.2	8.9/6.0	9.5/ /1.L	8.4/	2.5/	7.5/	2.0/	8.9/	1.9/ /57	8.4/	8.5/
Axle C weight.	1.5/	8.1/ 1.1.6	7.7/	8.2/	0.1/	7.3/	r.c/s.r	8.3/	3.6/	7. {	2.1/2.2	7.7/6.9	۲.۲/	3/2.5	3.4	8.3/
Axle B weight.	9,1/	8.5/	3.1/7.8	ණ	74/7-8	3.1/4.5	1.8/	8.5/	4.4	8	1,9/	7.5	<i>T</i>	3.7	5.L/ 2.L/	1,9/
Axle A weight.	5.9/ /5.8	5.7/	5.7/ 6.8	5.6/5.8	5.1/	7/2/	2.8/	3.5/	60/5.3	5.7/5.7	5.2/	5	5.9/5.7	5.5%	5.5/	5.7
WIM Speed	h٩	h9	h5	53	0,3	29	اه	۲9	N.	h 5	58	65	وبر	ヹ	FS	
Record No.	24387	24388	Lenh2	244 10	24436	24437	24465	99Hhz	86442	bbhh2	18342	24532	24553	24554	24581	24582
Time	80:01	80;01	51:01	(0:(5	10:23	(0:23	05;0)	10:30	L\$;01	LS:01	5h:01	53.20	10.52	(B.52	00:11	00;)
Pass	·-	σ	0.)	0)			2	12	1.3	1.3	ī	五	15	15	و	ع
Truck		7		٦	.,	7	(7		7		ч		2		7
Radar Speed	3	ょ	55	54	3	<u>۔</u> و	<u> </u>	6 5	53	S.4	ŝ	و٥	3	3	hS	СH
Pvmrt temp	2,07	20.5	21.0	21,0	13.5	23.5	27.0	27.0	ĬĘ.S	14.5	29.5	23.5	22,0	22.0	0.4.0	24,0

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Data *SPS PROJECT_ID Q400 rds 2 of 3 * DATE 11 / 27 / 2007	Sheet 21	* STATE_CODE	55
ds 3 of 3 * DATE	LTPP Traffic Data	*SPS PROJECT_ID	0020 000
	WIM System Test Truck Records 3 of 3	* DATE	11 / 27 /2007

	·	···		· · · · · · · · · · · · · · · · · · ·	·	· }	·····	· · · · · · · · · · · · · · · · · · ·	·	1	1		-		···	Ţ	1
E-F space																	
D-E space	ر ب د	0 T	4.0	4.0	J.	J, 0	÷	Î	4.0	f. 0							,
c-D space	32.8	31.9	32.8	31.9	32.8	32.0	32.9	32.0	32.7	31.9							
B-C space	4.3	4.3	Ч.3	4.3	4.3	4.3	۲ ۲	4.3	4.3	ų.3							
A-B space	٥.٢	6.91	٥٠٢١	6. <u></u>	n.o	0.17	0. L1.	16.9	0. []	0.U							
GVW	F ; F	67.5	H.17	69.7	77.5	1-29	72.9	4,99	75.9	(pd.3							
Axle F weight	ı											⁸⁰ .5.					
Axle E weight.	8.4/	7.3/6.7	9.5/	1.3/	9.0/	6.3/	8.7/	8-5/2-1	6.7/	1.2/5.4							3
Axle D weight.	4.6	7.1/6.2	8.9/	r.2/	8.5/	6.5/ 6.0	8.0/ P.8/	7.3/	0.8/).4/ (6.1							
Axle C weight.	4.9/ 1.1	7.4/ F.3/	8 L. L/2. 8. L/2. C	8.7/7.8	7.7/	7.8/	2.7/2	7.1/	1.5/	3/2.1							d by
Axle B weight.	7.4/	8.4	8.7/7.8	8.6/	1.7/1.7	8.1/7.6	1.3/	3/7.8	P. L	8.3/							Checked by
Axle A weight.	1.7/ 8.1/25 1.5/	T (6.0)	L'S/L'S	5.5/	P 5.6/ 1.7/ 1.7/ 8.5/ 8.8	5.3/ 8.1/.6 7.8/	25/21 1.3/28	1.9/	h:5/8.3	5.3/							_
WIM Speed	59	59	Ha	T	4S	7.5	59	09	方	وع							
Record No.	24604	24605	Z41.37	24641	119hz	24672	24697	24698	22LhZ	hZLhZ.							
Time	11:08	80:11	51:11	9);!!	£7:11	£2:11	18:14	18:41	11:34	6 8311							
Pass	5	7	81	100	Ы	19	cl	07	17	17							30
Truck		2	1.222.00	7		7		7		7							
Radar Speed	5	59	59	(و ک	54	25	9	(و)	ከ ግ	59					44444		led by_
Pvmt temp	24.5	24.5	13.0	23.0	18.5	10,5	07.	2.0	3	حر							Recorded by

-	OX.	9		E-F space														
	8			D-E space	0 7	<u>r.</u>	4.0	۵ ت	6		0 7	4.0	0,7	4.0	D. 7-	2		
55	0.400 0.700			C-D space	32.7	32.0	32.8	32.0	32.8	32.0	32.6	31.9	32.7	31.9	32.8	5		
	0	١. '		B-C space	4.3	4.3	4.3	4.3	43	4.3	4.3	£.7	4.2	7,	£.3	Z,		
		11 /27 / 2007		A-B space	0.,5	<u>ت</u> د_	٥.٢٧	20	٥.٢٧	6.(1)	0.6	١6.9	0,7	16.91	0.0	ક તો		
CODE	CI ID			GVW	P. H.	66.3	0.17	64.8	3'51	67.6	17.9	0.99	C. T.	66.9	-	8. Fd		
* STATE_CC	*SPS PROJECT	* DATE		Axle F weight														
* SI	*SP	* D/		Axle E weight.	9.3/	6.2/	57/	\$.8/ /7.0	8.9/	7.5/	9.0%	6.5/5.3	10,0	5.5/29	€°/ %3	6.8/		
				Axle D weight.	8.5/	6.3/	9.3/	F.7	1.8	ارة 1.9	2.4/	2.5/	8.i/ /8.e	1.0/ 5/2.6	8.5/	70/		
				Axle C weight.	7/1		7.6/	8.1/.3	7.3/	5"L/8"L	7.8/	9.2/	15/	(c. 1) (b. 5)	8.1/2.7	7.8/		
				Axle B weight.	1.0/ 1.1/	ربر) ۱۰۲/	62/	8/ 0.8/	7.5/ 7.8	82/2	H.L/	E4/	7.4/	5.0/	7.5/	71.00		
		jo i		Axle A weight.				Y.S/	8.5/	5.7/	2.3/	0.9/	5.5/	5.3/	9:3/15.6	5:5/		
	c Data	cords		WIM	hS	53	5.4	65	سر: ف	65	55	h.S	59	59	ور	59		
Sheet 2	LTPP Traffic Data	WIM System Test Truck Records		Record No.	27605	27606	859LZ	0H9LZ	276.58	65912	27690	27691	HLLZ	21112	1. PTT2	242		
	ΓΊ	tem Test		Time	ڻ:53	\$5:0	9.01	ڻ ن آ	80:J	9:0°	9:15	9:15	£2;b	9:23	9:30	9:30		
		WIM Sys		Pass			7	7	eΛ	3	T		7	5	و	೨		
				Truck	and the second	2		2	atom (PM	7		7		۲		N		
			Rev. 08/31/2001	Radar Speed	5	丢	.gs V/)	39	E	65	Ŋ	55	<u>د</u>	(K	59	\S		
			Rev. 08,	Pvmt temp	2	7	7	7.7	2.5	ارا اک	Ü	a	N.	57.50	<u> </u>	001		

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				E-F space																
				D-E space	Ş J	0.5	5	٥ ت	1,0	6,0	دن د	9	ر لر ه	0 7	J.	o Ť	i o	о. ;		
1	55 0160 6- 2	20000		C-D space	32.9	21.9	72.7	31.9	37.8	21.9	32.6	3(.9	32.8	32.0	32.7	32.0	72.7	≥ ≥		
				B-C space	4.3	4.3	" <u>1</u>	i.	5.	2	4.3	4.3	ئر	4.3	<u>2</u>	Ţ,	たっと	かって		
		11 /27/2007	20 7	A-B space	Ē	ف	17.0	- <u>o</u>	Ċ	0.17	0.7	16.9	ه کار ا	16.9	0,5	53	0.	في		
100	CT III			GVW	79	3	7.51	70.4	J. j.	9 89	77.5	66.2	14.9	72.2	75.7	75.1	h:SL	65.0		
Liu v	*SPS PROTECT ID	* DATE		Axle F weight																
3	C dS			Axle E weight.	9.2/	6.4/ 5.4	200	6.6/	69/	6.5%	33	23/19	8.9/ 7.9	1.0/m	3.7.7	h-7/2-L	53/ 61/	12/2.7		
				Axle D weight,	8.8	1.5/	6.1/)/mL	8.2/4.0	0.5/	25.3	15.4	2000	T.5/	9.c/	7.2/ 1/50	19.35 19.35 17.35 17.35	6.4/ 5.4		
				Axle C weight.	7.6/	5.4	1.5/	19/	12/21	8.4/	1.7	5.5	1.3/	7.4%	2.F/ 7.5	%. X	73,4	1. L		
		7		Axle B weight.	5-4	0.1/	75/	9.7	9.4/ 1.6	8.3/ 1.17	7.5/2.5	8.4/ 77.5	8.1/	0.8/	8#/ 7.2	6.5/	Ž.	2.7/		,
		2 of		Axle A weight.	5.7/	8.3/	5.5/	5.8/ /6.5	5.7/	(3	9.5/ /85	5.3/	b:5/55	63/6.5	9:5/	رد.و/ الو.ع	5.2/ 5.i	L'S/ks		
10	ic Data	scords		Speed	55	23	59	29	59	59	22	SY	Ç.	0	٦ 9	ž	S	N		
Choot 71	LTPP Traffic Data	Truck Records		Record No.	28025	28026	28051	28022	2807S	28076	226 (005	38 i of	28132	28133	<u>25 87</u>	28151	26173	28175		
		E		Time	94:01	%:이		<u>중:2</u>	10:1	10:1	50:11	11:09	2	3	11:23	11:24	23			
	***************************************	WIM System		Pass	5.	三	کینی	7	 	2	e5		<u></u>	90	3	5	12	9,		
				Truck	ممسينير	7	المراجعة	H	,	c1		d	المستقوي _{ة.}	7		7	سسبير	N		
			Rev. 08/31/2001	Radar Speed	FX.	S	6 -	5	2	2'	7.	か	0	S	き	د د	r	Z	****	
			Rev. 08	Pvmt temp	7	77	<u>o</u>	红	23.52	23.5	-1	[7]	29.5	25.	22	29	瓷	7° 27		

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				E-F space						3										
	ဥ			D-E space	4.0	0	٥ ټ	0 7	0 7	0)	0 h	- e	0	8 j	0,7	4.0	0. 12	ت ن ن	0	<u> </u>
55	0400 0200			C-D space	72.7	31.4	32.8	2	32.6	18 18	32.7	32.0	32.9	31.5	32.7	31.9	32.8	31.9	32.8	32.1
	0	_		B-C space	ペナ	たか	4,7	r.,	t, 3	300	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	27.	L. 7.	4,3	4:3	7	7	んり	みよ	4,7
		11 /288/2007		A-B space	0.7.	و	Ĺ	5	20	0.07	0.01	0.7.0		٠ <u>٠</u>	07	2	-	س و و	ē ģ	D.0
ODE	CT_ID			@VW	ا ق	51.9	2.31	H.2L	200	(2)	16.3	7.19	だ	13.0	00 <u>è</u>	4.190	7	76.2	2	69.1
* STATE_CODE	*SPS PROJECT_ID	* DATE		Axle F weight																
* S.1	*SP	, D		Axle E weight.	8.5/	67/5:3	8.8/6.3	C.0/	4.1/4.1		50 00 00 00 00	6.1/	2, 5 /x, 5	7.3/	1.99	7.1/6.3	9.0/	2.4	4.9/	ۇ. ۋ
				Axle D weight.	14.5	0.9/	8.1/ 8.0	1.9/ 1.7-1	4.p)	1.5/	8.4	6.5/ 75.7	7.6	7.3/	9-2/	3.5/	8.5/ /7.3	7.3/	6.5/	6:3/
			!	Axle C weight.	7.5/	%. % 17.3	245	78/7.9	21/12	1	1.1/.1	84/ 7.5	7.27	8.0/ 7.19	7.5/	6.0/ .69	2.7/	ê. i 7.0	1.3/	63/
		~ 4		Axle B weight.	22.	8.37	8.0/	8.9/	77/8.0	The state of the s	7.8/1.3	8.0/ 17.5	۲.۲/ ۲.۲/	1.3/	5,14	84/ 1.6	82/ 17.9	8.0/ 10.3	ارار المرار	\ \frac{1}{2} \
		i of		Axle A weight.	3:54	9.3/	5:5/ 15:5	6.1/ /6.4	5.8/5.9	3.5/5.2	43/US	5.4/	5.6/3	16.3/ 16.4	5.3/	5.5%		73	5.2/	55/6.0
11	c Data	cords		Speed	5	55	ડ	0,	To	(6.1	25	25	iv Q	٥٥	ゴ	ζ	9	E	7	5
Sheet 21	LTPP Traffic Data	Truck Re		Record No.	วะเกร	אלרוב	7,80,1	27602	27826	12812	27866	L98LZ	27895	27896	27918	2 M 19	27960	27961	3562	27996
	LI	WIM System Test Truck Records		Time	300	4:39	ر ا ا	g/k/b	9:53	4:59	10:01	10:01	% 9	<u>5</u> 0.0	9:10	9):01	5:0	Š	10:39	16:38
		WIM Sys		Pass	r	_	೧೮	حص	Œ	4	Ð	5		ت	7		13	7	4	()
		,		Truck		N	VO PARILLE	7	eq#Balinar#		Munimi	Ç	مبسوير	7		7	الاسترازيو ي	7	ga nje propinso	7
	· · · · · · · · · · · · · · · · · · ·		Rev. 08/31/2001	Radar Speed	<u>S</u>	×	S.	ુ	ĠS	j	N	n	<i>v</i>	3	50	2	25	5	ć,	3
			Rev. 08	Pvmt temp	2	75	5:57.	25.52	23.5	5.82	2	ぶ	5	٥	72	22	23	23	53	5.3

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6420060018_SPSWIM_TO_20_55_2.90_0400_post-Validation_sheet_21.doc

Checked by_

300

Recorded by_

Site: 550200

Beginning factors:

Speed Point (mph)	Name	Value
Overall		0/0
Front Axle	chynamic comp	\03
1-(80)	speed bin 1	3296/3476
2 ()	Z	3381/3566
3-(3	3414/3601
4 – (L -f	3315 /3497
5-(5	3262/3441

Errors:

	Speed Point 1	Speed Point 2	Speed Point 3	Speed Point 4	Speed Point 5
F/A		-4.6	- 4,8	-2.5	
Tandem		-0.4	-5,9	1,2	
GVW		~ (, 1	<u> </u>	0.6	

Adjustments:

	Raise	Lower	Percentage
Overall			
Front Axle	V		3.0
Speed Point 1			
Speed Point 2			
Speed Point 3		No. of the Control of	4,6
Speed Point 4	2 Miles		1.1
Speed Point 5			

End factors:

Speed Point (mph)	Name	Value
Overall		0/0
Front Axle	Agnonic comp	104
1 ()	Speed bin 1	3296/3476
2-()	2	3381/3566
3-(3	3571 /3767
4-()	Ч	3278/3459
5-(5	3262/3441

QUO Chools SPSWIM TO ED 35 ZED OFOOD Computations workshoot by did

f/2 = 11900 Veh 9 m = 77850 60 ff2 = 11650 2 veh (rout exte 65 5×w = 67800 3416 3381 3594 3414 3295 77850 3315 67800 145650 1 3605 3566 72825 3791 3601 2) M2020 3476 3497 1/2 -1.1 72343 (-.005) 55 -4.6 (72000) (11238) -8.8 -5.0 69536 (69160) (10743) - 2.5 65 0.6 (11486) (73236) 72765 (+1.1) (71174) (Inss) 1 Sisce Flz by 5 % [-5,3 [-1.8]

3,500

12 ise fle by 3.5%

183-107

34111

3601

3315 lower speed him 4 by 1.1%

3459

1801) 1119 11888

11546

TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

November 27, 2007

STATE: Wisconsin

SHRP ID: 550100

Photo 1 - Truck_1_Tractor_55_0100_11_27_07.JPG	2
Photo 2 - Truck_1_Trailer_Load_1_55_0100_11_27_07.JPG	
Photo 3 - Truck_1_Suspension_1_55_0100_11_27_07.JPG	
Photo 4 - Truck_1_Suspension_2_55_0100_11_27_07.JPG	
Photo 5 - Truck_1_Suspension_3_55_0100_11_27_07.JPG	
Photo 6 - Truck_2_Tractor_55_0100_11_27_07.JPG	
Photo 7 - Truck_2_Trailer_55_0100_11_27_07.JPG	
Photo 8 - Truck_2_Suspension_1_55_0100_11_27_07.JPG	
Photo 9 - Truck_2_Suspension_2_55_0100_11_27_07.JPG	
Photo 10 - Truck 2 Suspension 3 55 0100 11 27 07 IPG	



Photo 1 - Truck_1_Tractor_55_0100_11_27_07.JPG



Photo 2 - Truck_1_Trailer_Load_1_55_0100_11_27_07.JPG



Photo 3 - Truck_1_Suspension_1_55_0100_11_27_07.JPG



Photo 4 - Truck_1_Suspension_2_55_0100_11_27_07.JPG



Photo 5 - Truck_1_Suspension_3_55_0100_11_27_07.JPG



Photo 6 - Truck_2_Tractor_55_0100_11_27_07.JPG



Photo 7 - Truck_2_Trailer_55_0100_11_27_07.JPG



Photo 8 - Truck_2_Suspension_1_55_0100_11_27_07.JPG



Photo 9 - Truck_2_Suspension_2_55_0100_11_27_07.JPG



Photo 10 - Truck_2_Suspension_3_55_0100_11_27_07.JPG

ETG LTPP CLASS SCHEME, MOD 3

Axle 1 Weight Min *			-			2.5				2.5	3.5	3,5			2.5	3.5	3.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross Weight Min-Max		0.10-3.00	1.00-7.99	1.00-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12,00-19,99	12.00 >	20.00 >	1.00-11.99	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20,00 >	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00>	20.00 >
Spacing 8																														3.00-45.00
Spacing 7																				The second secon									3.00-45.00	3.00-45.00
Spacing 6	77718								312.00						***************************************													3.00-45.00	3.00-45.00	3.00-45.00
Spacing 5						700000000000000000000000000000000000000																				2.50-10.99	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 4																			1.00-11.99	1.00-11.99	2.50-6.30	2.50-11.99	12.00-27.00	2.50-6.30	11.00-26.00	2.50-11.99	6.00-24.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3			7,000,000										1.00-11.99	1.00-11.99	1.00-20.00	2.50-12.99	13.00-50.00	2.50-20.00	1.00-11.99	1.00-25.00	2.50-6.29	6.30-65.00	6.30-50.00	2.50-6.30	6.00-20.00	6.10-50.00	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 2							6.00-25.00	6.00-25.00	3.00-7.00	6.30-30,00	2.50-6.29	11.00-45.00	6.00-30.00	6.00-30.00	6.30-40.00	2.50-6.29	2.50-6.29	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 1		1.00-5.99	6,00-10,10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6.00-26.00	10.11-23.09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00
No. Axles		7	2	7	2	7	3	3	æ	33	e	3	4	4	4	4	4	4	ĸ	\$	S	w	\$	5	5	9	9	<u>r</u>	x	6
Vehicle Type	1	Motorcycle	Passenger Car	Other (Pickup/Van)	Bus	2D Single Unit	Car w/1 Axle Trailer	Other w/ I Axle Trailer	Bus	2D w/ 1 Axie Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 3SI	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/ 3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's
Class			7	60	4	S	7	6	4	'n	9	∞	7	3	S	-	%	×	3	w		6	6	6	=	10	12	13	13	13

Spacings in feet Weights in kips (Lbs/1000)
* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

Wisconsin SPS-1 (Lane 1)

	November 27, 2007	Installation Calibration
Speed Bin	Sensor 1 (Left)	Sensor 1 (Left)
1	3296	3296
2	3381	3381
3	3521	3414
4	3278	3315
5	3262	3262
	Sensor 2 (Right)	Sensor 2 (Right)
1	3476	3476
2	3566	3566
3	3767	3601
4	3459	3497
5	3441	3441
Dynamic comp	106	103